

The remote station ER-2014 provides 8 inputs and outputs, including 6 free inputs and outputs. There are 2 piezo-buzzer-outputs for the call messaging of bus-matrix-indicator, For group are operating according 4 outputs for displaying car position and 2 arrows per elevator. In addition, there are 2 Outputs for landing operation and special trip per elevator. You connect 2 speacers ( 8 ohms impedance) for the gong of the floor.
You can modulate your gong signal at the options (volume, peach,repetition and trips I which it sounds. ( Car Call Up and Down, Landing Call Up and Down, Special trip...)
The remote station have all necessary call-inputs and arrow-outputs (even for selective door-controlling).
The installation of Remote Station is in the standard shaft cable channel $90 \times 40$. You combinate the Bus and Power only with blue connection cable RJ-45-Cable.
If there is a optional shaftbus necessary, you can use the shaftbus No. 3 in the colour yellow.
The 7-pole Terminal below with the call-wires $2 x A \& 2 x B$ is reserved for the Doorside 1, the other Terminal above with $2 x C$ \& $2 x D$ is for the Doorside 2.
The connection of the Matrix-indicator of type ANZ-XX (ANZ-22, ANZ-32, ANZ.-33, ANZ52 \& ANZ-53) takes place on the black RJ-12 jack.
The yellow marked RJ-12 Terminal is for highrise TFT Graficdisplays with KW-busoperation.



## FUNCTION-VISUALISATION

When the ER-2014 connected with bus line and the controll is aktive, the green LED is blinking. In short circuit on the busline or malfunction expires or shine the LED. You can controll the Remote Station in Menu C6 Modul Monitor/ Remote Station ER01-16 and Remote Station ER 17-32, .. to 64.
For every remote station which function is ok, there will be shown an "E" in the display of the HPG-60. From left to right, you can see in the display all remote stations from the first floor to the hightest floor which are recognized in the system.

## ADRESS SETTING



## TERMINAL: MATRIX-INDICATOR TYPE ANZ-xx

The connection of the Matrix-indicator of type ANZ-XX (ANZ-22, ANZ-32, ANZ.-33, ANZ-52 \& ANZ-53) takes place on the black RJ-12 jack with the black RJ-12 cable.
Don't do the RJ-12 in the silver RJ-45 jack or the yellow marked RJ-12 jack!

## Connecting a TFT-Display at the ER-2014

The connection of a TFT-Display will be done at the yellow marked RJ-12 terminal with the standard $\mathrm{RJ}-12$ cable.

Don't do the RJ-12 in the silver RJ-45 jack or the RJ-12 jack of the matrix-indicators!

## Connecting several TFT-Displays at the ER-2014

With the help of a RJ-12-changer you can use serval TFT-Displays at the same output-terminal.
This is necessary if you have lifts with serval door-sides, or a groupe of lifts.


At the remote station ER-2014 there is a 2-pole DIL-Switch for activation the following functions:
1.) At the first switch you can switch ON the termination-resistors. Please switch ON the termination only at the last remote station!
2.) At the second switch you can activate the passive bus. A passive bus can only give out informations like for example arrows and car-position. Therefore the passive bus can work in the same address-room like the shaftbus no.1.

Schachtbus ER2014 mit einer
Schachttürseite
RJ-45 Buskabel \& Powerltg. zum


[^0]Maschinenraum Unten

Assembly in the shaft:
According to standart the floor computer strand along.integrated into the troughing. Our recommended standard throughing $90 \times 40 \mathrm{~mm}$ offers sufficiently place.

The lowest stop gets the floor computer with the marking HS01 assigned. The remote station should be approximately at the height of the door fighter.
The tablet cable for the door side 1 with a lenght of 2 metres is attached down to the remote station.
If a floor with front and back door should likewise be present in the floor (door side 29 then the tablet cable of the 2 landing cap panel is put above to the remote station.
Exactly the same as for the first floor for all other floors will proceed.
The inlet cable for the floor computer strand is put in either lowest or at the highest floor computer depending upon situation of the machine-room.

## Schachtbus ER2014 mit zwei Schachttürseiten

RJ-45 Buskabel \& Powerltg.zum Maschinenraum
 Unten

Gruppen-Schachtbus ER2014 mit
einer 2er Gruppe

| RJ-45 Buskabel \& Powerltg.zum Maschinenraum Oben |  |
| :--- | ---: |
| Anlage A1 | Anlage A2 |



## Assembly in the shaft:

According to standart the floor computer strand is along-intergrated into the throughing. Our recommended standart throughing $90 * 40 \mathrm{~mm}$ offers sufficiently place.

The lowest Stopp gets the remote station with teh marking STO1 assigned. The floor computer should be positioned approximately at height of the door fighter.

The tablet cable 1 with a length of 2 meters is attached down to the remote station.
The following functions are contained:

1) $2 x A$ landing call Up
2) $2 \times B$ landing call Down
3) 97 A arrow diplay Up A1
4) 98A arrow display Down A1

The tablet cable 2 with a length of 2 meters is attached down to the remote station.
The following functions are contained:
5) $2 x C$ free allocable
6) $2 \times D$ free allocable
7) 97B arrow diplay Up A2
8) 98B arrow display Down A2

Exactly the same as for the first floor for all other floors will proceed.
The inlet cable for the remote station strand isput in either lowest or at the highest remote station, depending upon situation of the machine-room.

Shaft bus wiring with remote station ER-2014 in a shaft of a single lift:


Shaft bus wiring with remote station ER-2014 in a very large shaft with two door-sides of a single lift:


Shaft bus wiring with remote station ER-2014 with a double group with common shaft:


Shaft bus wiring with remote station ER-2014 with a double group with separate shafts:


Shaft bus wiring with remote station ER-2014 with a 3- or 4-member group with common shafts to 32 floors:


KW Aufzugstechnik GmbH
Shaft bus wiring with remote station ER-2014 with a 3- or 4-member group with separate / very large shafts to 32 floors:



[^0]:    RJ-45 Buskabel \& Powerltg. Zum

